ABSTRACT

When an error is detected in coded data in the current frame, data separation section 201 separates the data into coding parameters first. Then, mode information decoding section 202 outputs decoding mode information in the previous frame and uses this as the mode information of the current frame. Furthermore, using the lag parameter code and gain parameter code of the current frame obtained at data separation section 201 and the mode information, lag parameter decoding section 204 and gain parameter decoding section 205 adaptively calculate a lag parameter and gain parameter to be used in the current frame according to the mode information.